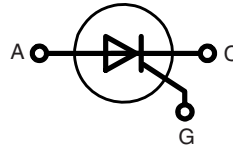


# Phase Control Thyristors

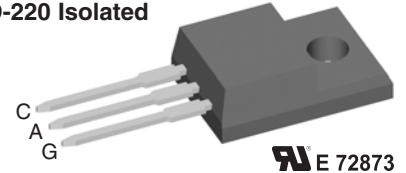
## Electrically Isolated Tab

$V_{RRM} = 800-1200 \text{ V}$   
 $I_{T(AV)M} = 16 \text{ A}$

| $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V | Type         |
|-----------------------------|-----------------------------|--------------|
| 800                         | 800                         | CS 22-08io1M |
| 1200                        | 1200                        | CS 22-12io1M |



TO-220 Isolated



A = Anode, C = Cathode, G = Gate  
 Tab = Isolated

| Symbol         | Conditions  | Maximum Ratings   |   |
|----------------|---|---|---|
| $I_{T(AV)M}$   | $T_C = 85^\circ\text{C}$ 180° sine <sup>①</sup>   | 16 A  |   |
|                | $T_A = 25^\circ\text{C}$ 180° sine <sup>②</sup>   | 2.5 A   |   |
| $I_{TSM}$      | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0 \text{ V}$  | t = 10 ms (50 Hz), sine 300 A<br>t = 8.3 ms (60 Hz), sine 320 A |   |
|                | $T_{VJ} = T_{VJM}$<br>$V_R = 0 \text{ V}$   | t = 10 ms (50 Hz), sine 260 A<br>t = 8.3 ms (60 Hz), sine 280 A |   |
|                | $I^2t$  | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0 \text{ V}$              | t = 10 ms (50 Hz), sine 450 A <sup>2</sup> s<br>t = 8.3 ms (60 Hz), sine 430 A <sup>2</sup> s |
|                |   | $T_{VJ} = T_{VJM}$<br>$V_R = 0 \text{ V}$                       | t = 10 ms (50 Hz), sine 340 A <sup>2</sup> s<br>t = 8.3 ms (60 Hz), sine 330 A <sup>2</sup> s |
| $(di/dt)_{cr}$ | $T_{VJ} = T_{VJM}$<br>f = 50Hz, $t_p = 200\mu\text{s}$<br>$V_D = \frac{2}{3} V_{DRM}$<br>$I_G = 0.08 \text{ A}$<br>$di_G/dt = 0.08 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 20 \text{ A}$ 150 A/ $\mu\text{s}$           |   |
|                |   | non repetitive, $I_T = I_{T(AV)M}$ 500 A/ $\mu\text{s}$         |   |
| $(dv/dt)_{cr}$ | $T_{VJ} = T_{VJM}$ , $V_{DR} = \frac{2}{3} V_{DRM}$<br>$R_{GK} = \infty$ , method 1 (linear voltage rise)   | 500 V/ $\mu\text{s}$  |   |
| $P_{GM}$       | $T_{VJ} = T_{VJM}$<br>$I_T = I_{T(AV)M}$  | $t_p = 30 \mu\text{s}$ 10 W<br>$t_p = 300 \mu\text{s}$ 5 W      |   |
| $P_{GAV}$      |   | 0.5 W   |   |
| $V_{RGM}$      |   | 10 V  |   |
| $T_{VJ}$       |   | -40...+150 °C   |   |
| $T_{VJM}$      |   | 150 °C  |   |
| $T_{stg}$      |   | -40...+125 °C   |   |
| $M_d$          | Mounting torque   | M 3 or UNC 4-40 0.5-0.8 Nm                                      |   |
| <b>Weight</b>  |   | 3 g   |   |

### Features

- Thyristor for frequencies up to 400Hz
- International standard package
- Epoxy meets UL 94V-0
- High performance glass passivated chip
- Long-term stability of leakage current and blocking voltage
- Plastic overmolded tab for electrical isolation

### Applications

- Motor control
- Power converter
- AC power controller
- Light and temperature control
- SCR for inrush current limiting in power supplies or AC drive

### Advantages

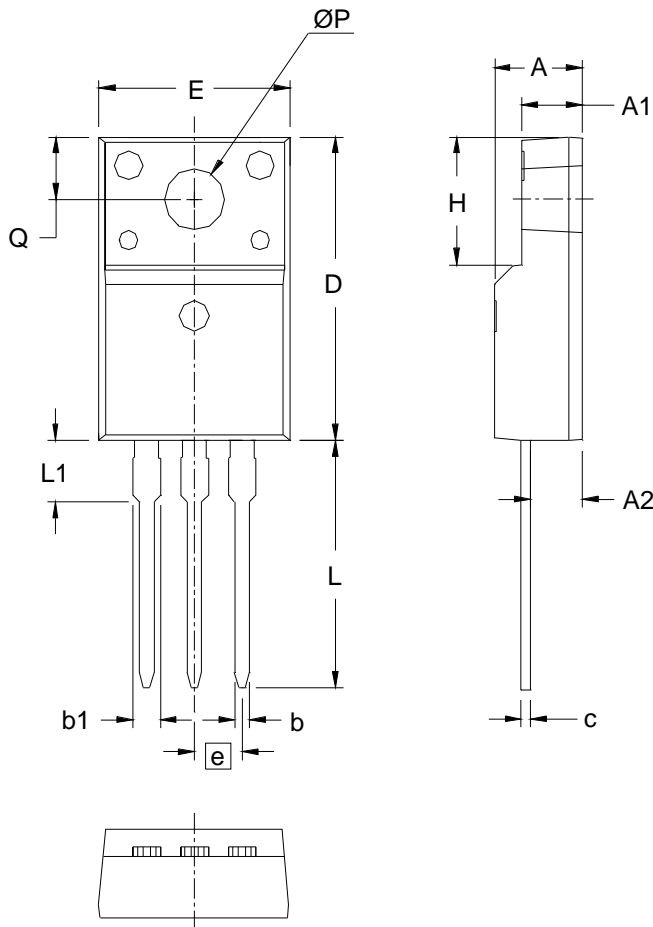
- Space and weight savings
- Simple mounting

<sup>①</sup> mounted on heatsink  
<sup>②</sup> without heatsink

Data according to IEC 60747

| Symbol     | Conditions   | Characteristic Values        |                     |
|------------|--|------------------------------|---------------------|
| $I_R, I_D$ | $T_{VJ} = T_{VJM}, V_R = V_{RRM}, V_D = V_{DRM}$   | $\leq$                       | 4 mA                |
| $V_T$      | $I_T = 30 \text{ A}, T_{VJ} = 25^\circ\text{C}$  | $\leq$                       | 1.4 V               |
| $V_{T0}$   | For power-loss calculations only ( $T_{VJ} = 150^\circ\text{C}$ )  |                              | 0.9 V               |
| $r_T$      |  |                              | 18 m $\Omega$       |
| $V_{GT}$   | $V_D = 6 \text{ V}$  | $T_{VJ} = 25^\circ\text{C}$  | $\leq$ 2.5 V        |
|            |  | $T_{VJ} = -40^\circ\text{C}$ | $\leq$ 3.5 V        |
| $I_{GT}$   | $V_D = 6 \text{ V}$  | $T_{VJ} = 25^\circ\text{C}$  | $\leq$ 30 mA        |
|            |  | $T_{VJ} = -40^\circ\text{C}$ | $\leq$ 50 mA        |
| $V_{GD}$   | $T_{VJ} = T_{VJM}, V_D = \frac{2}{3} V_{DRM}$  | $\leq$                       | 0.2 V               |
| $I_{GD}$   |  | $\leq$                       | 1 mA                |
| $I_L$      | $T_{VJ} = 25^\circ\text{C}, t_p = 10 \mu\text{s}$<br>$I_G = 0.08 \text{ A}, di_G/dt = 0.08 \text{ A}/\mu\text{s}$      | $\leq$                       | 100 mA              |
| $I_H$      | $T_{VJ} = 25^\circ\text{C}, V_D = 6 \text{ V}, R_{GK} = \infty$  | $\leq$                       | 80 mA               |
| $t_{gd}$   | $T_{VJ} = 25^\circ\text{C}, V_D = \frac{1}{2} V_{DRM}$<br>$I_G = 0.08 \text{ A}, di_G/dt = 0.08 \text{ A}/\mu\text{s}$ | $\leq$                       | 2 $\mu\text{s}$     |
| $R_{thJC}$ | DC current   |                              | 2.5 K/W             |
| $R_{thCH}$ | DC current   | typ.                         | 0.5 K/W             |
| $R_{thJA}$ | DC current   |                              | 50 K/W              |
| <b>a</b>   | Max. acceleration, 50 Hz   |                              | 50 m/s <sup>2</sup> |

### Package Outline



| SYM | INCHES   |      | MILLIMETERS |       |
|-----|----------|------|-------------|-------|
|     | MIN      | MAX  | MIN         | MAX   |
| A   | .177     | .193 | 4.50        | 4.90  |
| A1  | .092     | .108 | 2.34        | 2.74  |
| A2  | .101     | .117 | 2.56        | 2.96  |
| b   | .028     | .035 | 0.70        | 0.90  |
| b1  | .050     | .058 | 1.27        | 1.47  |
| c   | .018     | .024 | 0.45        | 0.60  |
| D   | .617     | .633 | 15.67       | 16.07 |
| E   | .392     | .408 | 9.96        | 10.36 |
| e   | .100 BSC |      | 2.54 BSC    |       |
| H   | .255     | .271 | 6.48        | 6.88  |
| L   | .499     | .523 | 12.68       | 13.28 |
| L1  | .119     | .135 | 3.03        | 3.43  |
| ØP  | .121     | .129 | 3.08        | 3.28  |
| Q   | .126     | .134 | 3.20        | 3.40  |

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